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# On the identification of the optimal partition for semidefinite optimization 

Ali Mohammad－Nezhad Tamás Terlaky

Department of Industrial and Systems Engineering
Lehigh University

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## Outline

Semidefinite optimization

Optimal partition

Identification of the optimal partition

Rounding procedure

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## Standard form of semidefinite optimization (SDO)

Let $C, A^{i}$ for $i=1, \ldots, m$, and $X: n \times n$ symmetric matrices
(P) $\min \left\{\langle C, X\rangle \mid\left\langle A^{i}, X\right\rangle=b_{i}, \quad i=1, \ldots, m, X \succeq 0\right\}$,
(D) $\quad \max \left\{b^{T} y \mid \sum_{i=1}^{m} y_{i} A^{i}+S=C, S \succeq 0, y \in \mathbb{R}^{m}\right\}$.

## Assumption

- There exists a primal-dual feasible $(X, y, S)$ so that $X, S \succ 0$.
- $A^{i}$ for $i=1, \ldots, m$ are linearly independent.
- We have strong duality:

$$
\begin{aligned}
\left\langle A^{i}, X\right\rangle & =b_{i}, \quad i=1, \ldots, m \\
\sum_{i=1}^{m} A^{i} y_{i}+S & =C \\
X S & =0, \quad X, S \succeq 0 .
\end{aligned}
$$

## Strict and maximal complementarity

Let $\mathcal{P}^{*}$ and $\mathcal{D}^{*}$ denote the primal and dual optimal sets.

## Definition

A primal-dual optimal solution $\left(X^{*}, y^{*}, S^{*}\right)$ is maximally complementary if

$$
\left(X^{*}, y^{*}, S^{*}\right) \in \operatorname{ri}\left(\mathcal{P}^{*} \times \mathcal{D}^{*}\right)
$$

A maximally complementary optimal solution is strictly complementary if

$$
X^{*}+S^{*} \succ 0
$$

Alternatively,

- $X^{*} \in \mathcal{P}^{*}$ and $S^{*} \in \mathcal{D}^{*}$ are maximally complementary optimal solutions if

$$
\mathcal{R}(X) \subset \mathcal{R}\left(X^{*}\right), \quad \forall X \in \mathcal{P}^{*}, \quad \mathcal{R}(S) \subset \mathcal{R}\left(S^{*}\right), \quad \forall S \in \mathcal{D}^{*}
$$

- $X^{*} \in \mathcal{P}^{*}$ and $S^{*} \in \mathcal{D}^{*}$ are strictly complementary optimal solutions if

$$
\mathcal{R}\left(X^{*}\right)+\mathcal{R}\left(S^{*}\right)=\mathbb{R}^{n}
$$

- A SDO problem may fail strict complementarity.


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## Optimal partition

Let $\left(X^{*}, y^{*}, S^{*}\right)$ be a maximally complementary optimal solution, and

$$
\mathcal{B}:=\mathcal{R}\left(X^{*}\right), \quad \mathcal{N}:=\mathcal{R}\left(S^{*}\right) .
$$

Then it is immediate that

- $\mathcal{R}(X) \subseteq \mathcal{B}$ and $\mathcal{R}(S) \subseteq \mathcal{N}$ for all $(X, y, S) \in \mathcal{P}^{*} \times \mathcal{D}^{*}$.
- $\operatorname{dim}(\mathcal{B})+\operatorname{dim}(\mathcal{N}) \leq n$.
- $\mathcal{B}$ and $\mathcal{N}$ are spanned by the eigenvectors of positive eigenvalues

$$
\mathcal{B}=\mathcal{R}\left(Q \Lambda\left(X^{*}\right)\right), \quad \mathcal{N}=\mathcal{R}\left(Q \Lambda\left(S^{*}\right)\right) .
$$

If $\operatorname{dim}(\mathcal{B})+\operatorname{dim}(\mathcal{N})<n$ :

- The orthogonal complement to $\mathcal{B}+\mathcal{N}$, which we call $\mathcal{T}$, is nonzero.
- The strict complementarity fails.


## Definition

The partition $(\mathcal{B}, \mathcal{N}, \mathcal{T})$ of $\mathbb{R}^{n}$ is called the optimal partition of an SDO problem.

## Optimal partition and optimal solutions

Let $Q:=\left[Q_{\mathcal{B}}, Q_{\mathcal{T}}, Q_{\mathcal{N}}\right]$ denote an orthonormal bases for $\mathcal{B}, \mathcal{N}$, and $\mathcal{T}$.
Let $n_{\mathcal{B}}:=\operatorname{dim}(\mathcal{B}), n_{\mathcal{N}}:=\operatorname{dim}(\mathcal{N})$, and $n_{\mathcal{T}}:=\operatorname{dim}(\mathcal{T})$.
Theorem (de Klerk et al.)
Every primal-dual optimal solution $(X, y, S) \in \mathcal{P}^{*} \times \mathcal{D}^{*}$ can be represented as

$$
X=Q_{\mathcal{B}} U_{X} Q_{\mathcal{B}}^{T}, \quad S=Q_{\mathcal{N}} U_{S} Q_{\mathcal{N}}^{T}
$$

where $U_{X} \in \mathbb{S}_{+}^{n_{\mathcal{B}}}$ and $U_{S} \in \mathbb{S}_{+}^{n_{\mathcal{N}}}$.

- If $n_{\mathcal{B}}>0$ and $X^{*} \in \operatorname{ri}\left(\mathcal{P}^{*}\right)$, then there exists $U_{X^{*}} \succ 0$.
- If $n_{\mathcal{N}}>0$ and $S^{*} \in \operatorname{ri}\left(\mathcal{D}^{*}\right)$, then there exists $U_{S^{*}} \succ 0$.

It can be deducted that

- $Q_{\mathcal{B}} \mathbb{S}_{+}^{n \mathcal{B}} Q_{\mathcal{B}}^{T}$ is the minimal face of $\mathbb{S}_{+}^{n}$ which contains $\mathcal{P}^{*}$.
- $Q_{\mathcal{N}} \mathbb{S}_{+}^{n}{ }_{\mathcal{N}} Q_{\mathcal{N}}^{T}$ is the minimal face of $\mathbb{S}_{+}^{n}$ which contains $\mathcal{D}^{*}$.


## Optimal partition and parametric SDO

Consider a pair of SDO problems with perturbed objective vector:

$$
\begin{array}{ll}
(\mathrm{P}(\omega)) & \min \left\{\langle C+\omega \bar{C}, X\rangle \mid\left\langle A^{i}, X\right\rangle=b_{i}, \quad i=1, \ldots, m, X \succeq 0\right\} \\
(\mathrm{D}(\omega)) \quad & \max \left\{b^{T} y \mid \sum_{i=1}^{m} y_{i} A^{i}+S=C+\omega \bar{C}, S \succeq 0, y \in \mathbb{R}^{m}\right\}
\end{array}
$$

- We assume that the Slater condition holds for all $\omega$ in a closed interval.

The optimal value function is defined as

$$
\phi(\omega):=\langle C+\omega \bar{C}, X(\omega)\rangle=b^{T} y(\omega),
$$

where ( $X(\omega), y(\omega), S(\omega))$ is a primal-dual optimal solution.

- The optimal value function is concave and piecewise algebraic (Nie et al.).
- Linearity and nonlinearity intervals are joined at the transition points.


## Optimal partition and parametric SDO

We can describe $\phi($.$) using the optimal partition:$

- Differentiability of $\phi($.$) at a given point \omega$ :
- Left and right derivatives.
- Constancy interval of the optimal partition $\Rightarrow$ linearity interval.
- Length of linearity interval.




## Optimal partition and parametric SDO

Identification of strongly unique optimal solutions $\Rightarrow$ Linearity intervals:

$$
\left\langle C, X^{*}\right\rangle \geq\langle C, \bar{X}\rangle+\alpha\left\|X^{*}-\bar{X}\right\|, \quad \forall \bar{X} \in \mathcal{P}^{*}
$$

or optimal solutions which are strongly unique in lower dimensions.



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## Central path

We aim to identify the sets of eigenvectors converging to an orthonormal bases.

- The central path equations are defined as

$$
\begin{aligned}
\left\langle A_{i}, X\right\rangle & =b_{i}, \quad i=1, \ldots, m, \\
\sum_{i=1}^{m} A_{i} y_{i}+S & =C \\
X S & =\mu I \\
X, S & \succeq 0 .
\end{aligned}
$$

- This system has a unique solution, the so called $\mu$-center, $\forall \mu>0$.
- The trajectory of the $\mu$-centers is known as the central path.
- As $\mu \rightarrow 0$, the trajectory converges to a solution in the optimal set.


## Condition number

We measure the magnitude of the eigenvalues using a condition number.

- The condition number $\sigma$ is defined as

$$
\begin{aligned}
\sigma_{\mathcal{B}} & := \begin{cases}\max _{X \in \mathcal{P}^{*}} \lambda_{\min }\left(Q_{\mathcal{B}}^{T} X Q_{\mathcal{B}}\right), & \mathcal{B} \neq\{0\}, \\
\infty, & \mathcal{B}=\{0\},\end{cases} \\
\sigma_{\mathcal{N}} & := \begin{cases}\max _{(y, S) \in \mathcal{D}^{*}} \lambda_{\min }\left(Q_{\mathcal{N}}^{T} S Q_{\mathcal{N}}\right), & \mathcal{N} \neq\{0\}, \\
\infty, & \mathcal{N}=\{0\},\end{cases} \\
\sigma & :=\min \left\{\sigma_{\mathcal{B}}, \sigma_{\mathcal{N}}\right\} .
\end{aligned}
$$

- By the Slater condition $\sigma$ is well-defined and positive.
- For some instances $\sigma$ can be doubly exponentially small.


## Lower bound for the condition number

## Lemma

Let $L$ denote the binary length of the largest absolute value of the entries in $b, C$, and $A^{i}$ for $i=1, \ldots, m$. Then we have

$$
\sigma \geq \min \left\{\frac{1}{r_{\mathcal{P}^{*}} \sum_{i=1}^{m}\left\|A^{i}\right\|}, \frac{1}{r_{\mathcal{D}^{*}}}\right\}
$$

where

- $R_{\mathcal{P}^{*}}$ is the radius of the ball which intersects $\mathcal{P}^{*}$,
- $R_{\mathcal{D}^{*}}$ is the radius of the ball which intersects $\mathcal{D}^{*}$.


## Regular system and degree of singularity

- The primal and dual feasible sets are regular systems:

$$
\begin{aligned}
& \left\{X \in \mathbb{S}^{n} \mid\left\langle A^{i}, X\right\rangle=b_{i}, i=1, \ldots, m\right\} \cap \operatorname{int}\left(\mathbb{S}_{+}^{n}\right) \neq \emptyset, \\
& \left\{S \in \mathbb{S}^{n} \mid \sum_{i=1}^{m} y_{i} A^{i}+S=C, \text { for some } y \in \mathbb{R}^{m}\right\} \cap \operatorname{int}\left(\mathbb{S}_{+}^{n}\right) \neq \emptyset .
\end{aligned}
$$

- The optimal set is not regular due to the complementarity condition:
- Primal optimal face: $Q_{\mathcal{B}} \mathbb{S}_{+}^{n \mathcal{B}} Q_{\mathcal{B}}^{T}$
- Dual optimal face: $Q_{\mathcal{N}} \mathbb{S}_{+}^{n} \mathcal{N} Q_{\mathcal{N}}^{T}$
- The number of regularization steps (Borwein and Wolkowicz) is called the degree of singularity.


## Distance to the optimal set

To identify eigenvectors converging to an orthonormal basis of $\mathcal{T}$ we need

- The distance of a central solution to the optimal set,
- The degree of singularity of the subspace which contains the optimal set.


## Lemma

Assume $n \mu \leq 1$. There exists $(X, y, S) \in \mathcal{P}^{*} \times \mathcal{D}^{*}$ so that

$$
\|X(\mu)-X\| \leq \kappa(n \mu)^{\gamma}, \quad\|S(\mu)-S\| \leq \kappa(n \mu)^{\gamma},
$$

where

- $\gamma=2^{-d\left(\operatorname{lin}\left(\mathcal{P}^{*} \times \mathcal{D}^{*}\right), \mathbb{S}_{+}^{n}\right)}$,
- $d\left(\operatorname{lin}\left(\mathcal{P}^{*} \times \mathcal{D}^{*}\right), \mathbb{S}_{+}^{n}\right)$ is the degree of singularity of the minimal subspace containing the optimal set,
- $\kappa$ is a positive condition number.
- In general, we have $\gamma \geq \frac{1}{2^{n-1}}$ for $n \geq 2$.
- If the strict complementarity holds, then $\gamma=\frac{1}{2}$.


## Bounds for the eigenvalues

## Theorem

For a central solution $(X(\mu), y(\mu), S(\mu))$ with $n \mu \leq 1$ it holds that:

1. For $i=1, \ldots, n_{\mathcal{B}}$ we have

$$
\lambda_{[n-i+1]}(S(\mu)) \leq \frac{n \mu}{\sigma}, \quad \lambda_{[i]}(X(\mu)) \geq \frac{\sigma}{n} .
$$

2. For $i=1, \ldots, n_{\mathcal{N}}$ we have

$$
\lambda_{[i]}(S(\mu)) \geq \frac{\sigma}{n}, \quad \lambda_{[n-i+1]}(X(\mu)) \leq \frac{n \mu}{\sigma} .
$$

Furthermore, we have

$$
\begin{array}{ll}
\lambda_{[n-i+1]}(X(\mu)) \leq \kappa \sqrt{n}(n \mu)^{\gamma}, & \lambda_{[i]}(S(\mu)) \geq \frac{\mu}{\kappa \sqrt{n}(n \mu)^{\gamma}}, i=1, \ldots, n_{\mathcal{N}}+n_{\mathcal{T}}, \\
\lambda_{[n-i+1]}(S(\mu)) \leq \kappa \sqrt{n}(n \mu)^{\gamma}, & \lambda_{[i]}(X(\mu)) \geq \frac{\mu}{\kappa \sqrt{n}(n \mu)^{\gamma}}, i=1, \ldots, n_{\mathcal{B}}+n_{\mathcal{T}} .
\end{array}
$$

- If $n_{\mathcal{T}}>0$, then we have $\kappa \geq \frac{1}{n}$, and $\frac{1}{2^{n-1}} \leq \gamma \leq \frac{1}{2}$.


## Identification of eigenvectors converging to $\mathcal{B}, \mathcal{N}$, and $\mathcal{T}$

In general, there exist three sets of eigenvectors $q_{i}(\mu)$ for which

- $\lambda_{i}(X(\mu))$ converges to a positive value and $\lambda_{i}(S(\mu))$ converges to 0 ;
- $\lambda_{i}(S(\mu))$ converges to a positive value and $\lambda_{i}(X(\mu))$ converges to 0 ;
- both $\lambda_{i}(X(\mu))$ and $\lambda_{i}(S(\mu))$ converge to 0,
where $\lambda_{i}(X(\mu))$ and $\lambda_{i}(S(\mu))$ correspond to the eigenvector $q_{i}(\mu)$.
- As $\mu \rightarrow 0$, the eigenvectors converge to an orthonormal bases for $\mathcal{B}, \mathcal{N}$, and $\mathcal{T}$.


## Theorem

If $\mu$ satisfies

$$
\mu<\min \left\{\frac{1}{n}\left(\frac{\sigma}{\kappa n^{\frac{3}{2}}}\right)^{\frac{1}{\gamma}}, \frac{\sigma^{2}}{n^{2}}, \frac{1}{n}\right\},
$$

then we can identify the sets of eigenvectors converging to an orthonormal bases for $\mathcal{B}, \mathcal{N}$, and $\mathcal{T}$.

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## Approximate maximally complementary solution

- We do not have the exact orthonormal bases for $\mathcal{B}, \mathcal{N}$ and $\mathcal{T}$ :
- An exact solution cannot be obtained from a given central solution.
- If we project $(X(\mu), y(\mu), S(\mu))$ onto the boundary of the cone:
- The solution has zero complementary gap.
- The solution is $\epsilon$-infeasible.
- The solution is called approximate maximally complementary.

The eigenvectors of $X(\mu)$ and $S(\mu)$ can be rearranged so that

$$
Q(\mu):=\left[Q_{\mathcal{B}}(\mu), Q_{\mathcal{T}}(\mu), Q_{\mathcal{N}}(\mu)\right],
$$

if $\mu$ allows for the identification of eigenvectors.

$$
Q(\mu)^{T} X(\mu) Q(\mu)=\left[\begin{array}{ccc}
\Lambda_{\mathcal{B}}(X(\mu)) & 0 & 0 \\
0 & \Lambda_{\mathcal{T}}(X(\mu)) & 0 \\
0 & 0 & \Lambda_{\mathcal{N}}(X(\mu))
\end{array}\right]
$$

- $\Lambda_{\mathcal{T}}(X(\mu)) \rightarrow 0$ and $\Lambda_{\mathcal{N}}(X(\mu)) \rightarrow 0$ as $\mu \rightarrow 0$.
- We get a complementary solution if we discard $\Lambda_{\mathcal{T}}(X(\mu))$ and $\Lambda_{\mathcal{N}}(X(\mu))$.


## Primal auxiliary problem

Let $\bar{A}^{i}:=Q(\mu)^{T} A^{i} Q(\mu)$.

- For the primal problem we solve

$$
\begin{aligned}
\min & \left\|\epsilon_{p}\right\|^{2}+\|\Delta X\|^{2} \\
\text { s.t. } & \left\langle\bar{A}_{\mathcal{B}}^{i}, \Delta X\right\rangle-\left(\epsilon_{p}\right)_{i}=\left\langle\bar{A}_{\mathcal{T}}^{i}, \Lambda_{\mathcal{T}}(X(\mu))\right\rangle+\left\langle\bar{A}_{\mathcal{N}}^{i}, \Lambda_{\mathcal{N}}(X(\mu))\right\rangle, \quad i=1, \ldots, m .
\end{aligned}
$$

- The optimal solution $\left(\epsilon_{p}^{*}, \Delta X^{*}\right)$ to the auxiliary problem yields

$$
\tilde{X}_{\mathcal{B}}:=\Lambda_{\mathcal{B}}(X(\mu))+\Delta X^{*}
$$

so that

$$
\left\langle\bar{A}_{\mathcal{B}}^{i}, \tilde{X}_{\mathcal{B}}\right\rangle=b_{i}+\left(\epsilon_{p}^{*}\right)_{i}, \quad i=1, \ldots, m
$$

- Thus, $\tilde{X}_{\mathcal{B}}$ has $\left\|\epsilon_{p}^{*}\right\|$ infeasibility for the primal constraints.


## Dual auxiliary problem

Let $E$ denote a residual matrix as

$$
E:=\left[\begin{array}{ccc}
E_{\mathcal{B}} & E_{\mathcal{B} \mathcal{T}} & E_{\mathcal{B N}} \\
E_{\mathcal{T B}} & E_{\mathcal{T}} & E_{\mathcal{T N}} \\
E_{\mathcal{N B}} & E_{\mathcal{N} \mathcal{T}} & 0
\end{array}\right] .
$$

For the dual problem we solve

$$
\begin{array}{ll}
\min & \|E\|^{2}+\|\Delta y\|^{2}+\|\Delta S\|^{2} \\
\text { s.t. } & \sum_{i=1}^{m} \Delta y_{i} \bar{A}^{i}+\left[\begin{array}{ccc}
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & \Delta S
\end{array}\right]-E=\left[\begin{array}{ccc}
\Lambda_{\mathcal{B}}(S(\mu)) & 0 & 0 \\
0 & \Lambda_{\mathcal{T}}(S(\mu)) & 0 \\
0 & 0 & 0
\end{array}\right] .
\end{array}
$$

- The optimal solution $\left(E^{*}, \Delta y^{*}, \Delta S^{*}\right)$ gives

$$
\begin{aligned}
\tilde{y}_{i} & :=y_{i}(\mu)+\Delta y_{i}^{*}, \quad i=1, \ldots, m, \\
\tilde{S}_{\mathcal{N}} & :=\Lambda_{\mathcal{N}}(S(\mu))+\Delta S^{*} .
\end{aligned}
$$

## Cone feasibility

Let $\pi_{p}$ and $\pi_{d}$ denote parameters dependent on linear mapping $\mathcal{A}$ and $Q(\mu)$, and

$$
r(n):=\frac{n(n+1)}{2} .
$$

- If $\mu$ is sufficiently small, then the rounded solution is cone feasible.


## Theorem

Let $\vartheta_{1}:=2 n^{2}\|\mathcal{A}\|^{2}, \vartheta_{2}:=2 \kappa n \sqrt{n n_{\mathcal{T}}}\|\mathcal{A}\|^{2}$, and let
$\tilde{\mu}:=\min \left\{\frac{\sigma^{2}}{\vartheta_{1} \max \left\{\pi_{p} \sqrt{r\left(n_{\mathcal{B}}\right) n_{\mathcal{N}}}, \pi_{d \sqrt{m n_{\mathcal{B}}}}\right\}}, \frac{1}{n}\left(\frac{\sigma}{\vartheta_{2} \max \left\{\pi_{p} \sqrt{r\left(n_{\mathcal{B}}\right)}, \pi_{d} \sqrt{m}\right\}}\right)^{\frac{1}{\gamma}}\right\}$.
If $\mu \leq \tilde{\mu}$, then we have $\tilde{X}_{\mathcal{B}}, \tilde{S}_{\mathcal{N}} \succ 0$.

- Only $\mathcal{O}\left(\max \left\{n_{\mathcal{B}}^{6}, m^{3}\right\}\right)$ arithmetic operations are needed.


## Summary

- Introduction of the optimal partition.
- Application of optimal partition in sensitivity analysis.
- Identification of eigenvectors converging to an orthonormal bases.
- A rounding procedure for an approximate maximally complementary solution.


# Thank you for your attention Any questions? 

